

On Approximation of an Optimal Control Problem for a Linear Elliptic Equation with Unbounded Coefficients

Peter Kogut

Department of Differential Equations
Dnipropetrovsk National University, Ukraine

le CNAM, Paris, 2013.

Control Object: Linear Diffusion Elliptic Equation

Let Ω be a bounded open connected subset of \mathbb{R}^N ($N \geq 3$) with Lipschitz boundary $\partial\Omega = \Gamma_D \cup \Gamma_N$, where Γ_D and Γ_N have positive $(N-1)$ -dimensional measures.

$$\begin{aligned} -\operatorname{div}(\nabla y + \mathbf{A}(\mathbf{x})\nabla y) &= f && \text{in } \Omega, \\ y &= 0 && \text{on } \Gamma_D, \\ \frac{\partial y}{\partial \nu_{\mathbf{A}}} &= u && \text{on } \Gamma_N, \end{aligned}$$

here $u \in L^2(\Gamma_N)$ is a control, $f \in H^{-1}(\Omega)$ is a given distribution.

Matrix of Unbounded Coefficients

In applications, the stream matrix $\mathbf{A}(\mathbf{x}) = [\mathbf{a}_{ij}(\mathbf{x})]_{i,j=1,\dots,N}$ is skew-symmetric, $\mathbf{a}_{ij}(\mathbf{x}) = -\mathbf{a}_{ji}(\mathbf{x})$, measurable and may admit unremovable singularity, namely, **belongs to the space** $L^2(\Omega; \mathbb{S}^N) = L^2(\Omega)^{\frac{N(N-1)}{2}}$ (rather than L^∞).

Definition

We say that $y = y(A, f, u)$ is a **weak solution** to the problem

$$\begin{aligned} -\operatorname{div}(\nabla y + A(x)\nabla y) &= f && \text{in } \Omega, \\ y &= 0 && \text{on } \Gamma_D, \quad \frac{\partial y}{\partial \nu_A} = u && \text{on } \Gamma_N, \end{aligned}$$

if $y \in H_0^1(\Omega; \Gamma_D)$ and

$$\begin{aligned} \int_{\Omega} (\nabla \varphi, \nabla y)_{\mathbb{R}^N} dx + \underbrace{\int_{\Omega} (\nabla \varphi, A(x)\nabla y)_{\mathbb{R}^N} dx}_{[y, \varphi]} \\ = \langle f, \varphi \rangle_{H^{-1}(\Omega; \Gamma_D); H_0^1(\Omega; \Gamma_D)} + \int_{\Gamma_N} u \varphi d\mathcal{H}^{N-1}, \quad (1) \end{aligned}$$

for all elements $\varphi \in C_0^\infty(\mathbb{R}^N; \Gamma_D)$.

Lemma

Let $u \in L^2(\Gamma_N)$ be a given control. If $y \in H_0^1(\Omega; \Gamma_D)$ is a weak solution to the above boundary value problem, then y belongs to the set D , i.e. the following relation holds true

$$\left| \int_{\Omega} (\nabla \varphi, A(x) \nabla y)_{\mathbb{R}^N} dx \right| \leq c(y) \left(\int_{\Omega} |\nabla \varphi|_{\mathbb{R}^N}^2 dx \right)^{1/2} \quad \forall \varphi \in C_0^\infty(\mathbb{R}^N; \Gamma_D)$$

with some constant $c(y)$ depending on y .

Setting $[y, \varphi] = \int_{\Omega} (\nabla \varphi, A(x) \nabla y)_{\mathbb{R}^N} dx$, $\forall y \in D$, $\forall \varphi \in C_0^\infty(\mathbb{R}^N; \Gamma_D)$, we can define the bilinear form $[y, \varphi]$ for all $\varphi \in H_0^1(\Omega; \Gamma_D)$ using the rule

$$[y, \varphi] = \lim_{\varepsilon \rightarrow 0} [y, \varphi_\varepsilon], \quad (2)$$

where $\{\varphi_\varepsilon\}_{\varepsilon > 0} \subset C_0^\infty(\mathbb{R}^N; \Gamma_D)$ and $\varphi_\varepsilon \rightarrow \varphi$ strongly in $H_0^1(\Omega; \Gamma_D)$. In this case the value $[v, v]$ is finite for every $v \in D$.

The energy identity

Passing to the limit in

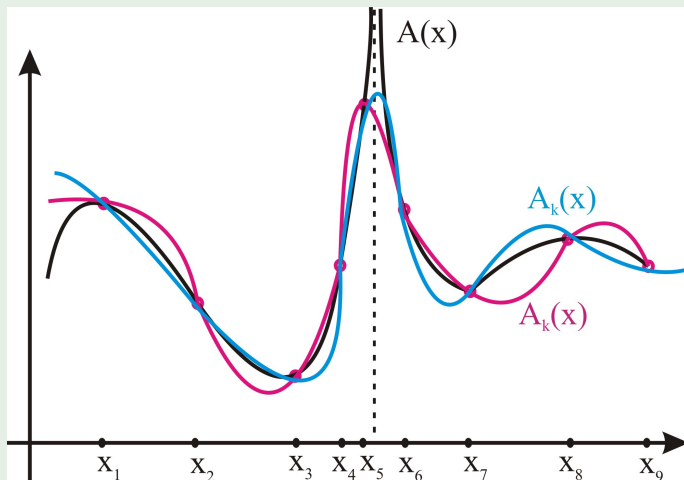
$$\int_{\Omega} (\nabla \varphi_{\varepsilon}, \nabla y)_{\mathbb{R}^N} dx + \underbrace{\int_{\Omega} (\nabla \varphi_{\varepsilon}, \mathbf{A}(x) \nabla y)_{\mathbb{R}^N} dx}_{[y, \varphi_{\varepsilon}]} = \langle f, \varphi_{\varepsilon} \rangle_{H^{-1}(\Omega; \Gamma_D); H_0^1(\Omega; \Gamma_D)} + \int_{\Gamma_N} u \varphi_{\varepsilon} d\mathcal{H}^{N-1}, \quad (3)$$

as $\varphi_{\varepsilon} \rightarrow y$ in $H_0^1(\Omega; \Gamma_D)$, we immediately come to the relation (**the energy identity for weak solutions**)

$$\int_{\Omega} (\nabla y, \nabla y)_{\mathbb{R}^N} dx + [y, y] = \langle f, y \rangle_{H^{-1}(\Omega; \Gamma_D); H_0^1(\Omega; \Gamma_D)} + \int_{\Gamma_N} uy d\mathcal{H}^{N-1}, \quad (4)$$

Example

The main idea of any numerical scheme



Approximable Solutions

A function $y^* = y^*(f, u)$ is called an approximable solution to the above boundary value problem if it can be attained by weak solutions $\{y_k\}_{k \in \mathbb{N}}$ to the boundary value problems

$$\begin{aligned} -\operatorname{div}(\nabla y + A_k(x)\nabla y) &= f && \text{in } \Omega, \\ y &= 0 && \text{on } \Gamma_D, \\ \frac{\partial y}{\partial \nu_{A_k}} &= u && \text{on } \Gamma_N, \end{aligned}$$

where $\{A_k\}_{k=1}^{\infty} \subset L^{\infty}(\Omega; \mathbb{S}^N)$ are such that $A_k \rightarrow A$ strongly in $L^2(\Omega; \mathbb{S}^N)$.

A trivial analysis of numerical approximations. Step 1.

The boundary value problem

$$\begin{aligned}
 -\operatorname{div}(\nabla y + A_k(x)\nabla y) &= f && \text{in } \Omega, \\
 y &= 0 && \text{on } \Gamma_D, \quad \frac{\partial y}{\partial \nu_{A_k}} = u && \text{on } \Gamma_N,
 \end{aligned}$$

has a unique solution $y_k = y(A_k, f, u) \in H_0^1(\Omega; \Gamma_D)$ for every $k \in \mathbb{N}$.
Moreover,

$$\begin{aligned}
 \int_{\Omega} (\nabla y_k, \nabla y_k)_{\mathbb{R}^N} dx + \underbrace{\int_{\Omega} (\nabla y_k, A_k(x)\nabla y_k)_{\mathbb{R}^N} dx}_{[y_k, y_k]=0} \\
 = \langle f, y_k \rangle_{H^{-1}(\Omega; \Gamma_D); H_0^1(\Omega; \Gamma_D)} + \int_{\Gamma_N} u y_k d\mathcal{H}^{N-1}, \quad (5)
 \end{aligned}$$

where $A_k \rightarrow A$ strongly in $L^2(\Omega; \mathbb{S}^N)$ and $\{A_k\}_{k=1}^{\infty} \subset L^{\infty}(\Omega; \mathbb{S}^N)$.

A trivial analysis of numerical approximations. Step 2.

A priori estimate

$$\|y_k\|_{H_0^1(\Omega; \Gamma_D)} \leq \|f\|_{H^{-1}(\Omega; \Gamma_D)} + \|u\|_{L^2(\Gamma_N)}, \quad \forall k \in \mathbb{N}.$$

Hence,

$$y_k \rightharpoonup y^* \quad \text{weakly in } H_0^1(\Omega; \Gamma_D),$$

where $y^* = y^*(f, u)$ is a weak solution to the original problem

$$\begin{aligned} -\operatorname{div}(\nabla y + A(x)\nabla y) &= f && \text{in } \Omega, \\ y &= 0 && \text{on } \Gamma_D, \quad \frac{\partial y}{\partial \nu_A} = u && \text{on } \Gamma_N. \end{aligned}$$

A trivial analysis of numerical approximations. Step 3.

Since

$$\int_{\Omega} (\nabla y_k, \nabla y_k)_{\mathbb{R}^N} dx = \langle f, y_k \rangle_{H^{-1}(\Omega; \Gamma_D); H_0^1(\Omega; \Gamma_D)} + \int_{\Gamma_N} u y_k d\mathcal{H}^{N-1}, \quad (6)$$

it follows from the weak convergence $\nabla y_k \rightharpoonup \nabla y^*$ in $L^2(\Omega; \mathbb{R}^N)$ that

$$\int_{\Omega} (\nabla y^*, \nabla y^*)_{\mathbb{R}^N} dx \leq \langle f, y^* \rangle_{H^{-1}(\Omega; \Gamma_D); H_0^1(\Omega; \Gamma_D)} + \int_{\Gamma_N} u y^* d\mathcal{H}^{N-1}. \quad (7)$$

On the other hand, we have the energy identity

$$\int_{\Omega} (\nabla y^*, \nabla y^*)_{\mathbb{R}^N} dx + [y^*, y^*] = \langle f, y^* \rangle_{H^{-1}(\Omega; \Gamma_D); H_0^1(\Omega; \Gamma_D)} + \int_{\Gamma_N} u y^* d\mathcal{H}^{N-1}. \quad (8)$$

Conclusion 1.

If y^* is a weak H^1 -limit of approximation solutions $\{y_k\}_{k \in \mathbb{N}}$, then

$$[y^*, y^*] \geq 0 !$$

Conclusion 2.

If for a given control $u \in L^2(\Gamma_N)$ there exists an element $v \in D$ such that $[v, v] < 0$ then the boundary value problem

$$\begin{aligned} -\operatorname{div}(\nabla y + A(x)\nabla y) &= f && \text{in } \Omega, \\ y &= 0 && \text{on } \Gamma_D, \quad \frac{\partial y}{\partial \nu_A} = u && \text{on } \Gamma_N, \end{aligned}$$

has more than one weak solution.

The Main Difficulty

The original boundary value problems may admit **infinitely many weak solutions** which can be divided into two classes: **approximable and non-approximable solutions**.

Setting of OCP

Let $f \in H^{-1}(\Omega; \Gamma_D)$ and $y_d \in H_0^1(\Omega, \Gamma_D)$ be given distributions and let $A \in L^2(\Omega; \mathbb{S}^N)$ be a given matrix. We consider the following OCP:

$$\text{Minimize } I(u, y) = \|y - y_d\|_{H_0^1(\Omega; \Gamma_D)}^2 + \|u\|_{L^2(\Gamma_N)}^2 \quad (9)$$

subject to constrains

$$-\operatorname{div}(\nabla y + A(x)\nabla y) = f \quad \text{in } \Omega, \quad (10)$$

$$y = 0 \text{ on } \Gamma_D, \quad \partial y / \partial \nu_A = u \text{ on } \Gamma_N, \quad (11)$$

$$u \in L^2(\Gamma_N). \quad (12)$$

Here $\frac{\partial y}{\partial \nu_A} = \sum_{i,j=1}^N (\delta_{ij} + a_{ij}(x)) \frac{\partial y}{\partial x_j} \cos(\nu, x_i)$, δ_{ij} is Kronecker's delta, ν is the outward unit normal vector at Γ_N to Ω .

Definition

We call the pair (u, y) **admissible to OCP** (9)–(12) if $u \in L^2(\Gamma_N)$, $y \in D$, and (u, y) are related by identity (1). We denote by Ξ the set of all admissible pairs for OCP (9)–(12). We call the pair (u^0, y^0) **optimal** to (9)–(12) if $(u^0, y^0) \in \Xi$ and $l(u^0, y^0) = \inf_{(u, y) \in \Xi} l(u, y)$.

Theorem

OCP (9)–(12) has a unique solution for each $f \in H^{-1}(\Omega; \Gamma_D)$, $A \in L^2(\Omega; \mathbb{S}^N)$, and $y_d \in H_0^1(\Omega; \Gamma_D)$.

Theorem

If matrix $A \in L^2(\Omega; \mathbb{S}^N)$ is such that $[y, y] = 0 \forall y \in D$, then a unique solution to (9)–(12) is variational, i.e. it can be attained by solutions to similar OCPs with L^∞ -approximated matrix A .

Let $A \in L^2(\Omega; \mathbb{S}^N)$ be a stream matrix. For a given sequence $\{\varepsilon > 0\}$ we consider the cut-off operators $\mathbf{T}_\varepsilon : \mathbb{S}^N \rightarrow \mathbb{S}^N$ defined by the rule $\mathbf{T}_\varepsilon(A) = [T_\varepsilon(a_{ij})]_{i,j=1}^N \forall \varepsilon > 0$, where $T_\varepsilon : \mathbb{R} \rightarrow \mathbb{R}$ is the truncation function

$$T_\varepsilon(s) = \max \{ \min \{ s, \varepsilon^{-1} \}, -\varepsilon^{-1} \}.$$

We associate with such operators the following set of subdomains $\{\Omega_\varepsilon = \Omega \setminus Q_\varepsilon\}_{\varepsilon > 0}$ of Ω where

$$Q_\varepsilon = \text{closure} \left\{ x \in \Omega : \|A(x)\|_{\mathbb{S}^N} := \max_{i,j=1,\dots,N} |a_{ij}(x)| \geq \varepsilon^{-1} \right\}.$$

Definition

We call $A \in L^2(\Omega; \mathbb{S}^N)$ a **funnel-type matrix** if there exists a strictly decreasing sequence $\{\varepsilon\}$ converging to 0 such that the corresponding sets $\{\Omega_\varepsilon\}_{\varepsilon>0}$ possess the following properties:

- (i) $\Omega_\varepsilon \subset \Omega$ are open connected subsets with Lipschitz boundaries and $\exists \delta > 0$, such that $\partial\Omega \subset \partial\Omega_\varepsilon$ and $\text{dist}(\Gamma_\varepsilon, \partial\Omega) > \delta, \forall \varepsilon > 0$, where $\Gamma_\varepsilon = \partial\Omega_\varepsilon \setminus \partial\Omega$.
- (ii) The surface measure of the boundaries of holes $Q_\varepsilon = \Omega \setminus \Omega_\varepsilon$ is small enough: $\mathcal{H}^{N-1}(\Gamma_\varepsilon) = o(\varepsilon) \quad \forall \varepsilon > 0$.
- (iii) For any element $h \in D$ there is a constant $c(h)$ depending on h and independent of ε such that

$$\left| \int_{Q_\varepsilon} (\nabla\varphi, A(x)\nabla h)_{\mathbb{R}^N} dx \right| \leq c(h) \sqrt{\frac{|\Omega \setminus \Omega_\varepsilon|}{\varepsilon}} \left(\int_{Q_\varepsilon} |\nabla\varphi|_{\mathbb{R}^N}^2 dx \right)^{1/2}$$

for all $\varphi \in C_0^\infty(\mathbb{R}^N; \Gamma_D)$.

Properties of funnel-type matrices

- Each of the sets Ω_ε is locally located on one side of its Lipschitz boundary $\partial\Omega_\varepsilon$;
- $\forall \varepsilon$ $\partial\Omega_\varepsilon$ can be divided into three parts $\partial\Omega_\varepsilon = \Gamma_D \cup \Gamma_N \cup \Gamma_\varepsilon$;
- the condition $\mathcal{H}^{N-1}(\Gamma_\varepsilon) = o(\varepsilon) \quad \forall \varepsilon > 0$. excludes the appearance of self-similar domains Ω_ε with some fractal behavior of the boundaries;
- the sequence $\{\Omega_\varepsilon\}_{\varepsilon>0}$ is monotonically expanding, i.e., $\Omega_{\varepsilon_k} \subset \Omega_{\varepsilon_{k+1}}$ for all $\varepsilon_k > \varepsilon_{k+1}$, and perimeters of Ω_ε tend to zero as $\varepsilon \rightarrow 0$, namely $|\Omega \setminus \Omega_\varepsilon| = o(\varepsilon^2)$ and, hence,

$$\frac{\varepsilon \mathcal{H}^{N-1}(\Gamma_\varepsilon)}{|\Omega \setminus \Omega_\varepsilon|} = O(1);$$

- $\chi_{\Omega_\varepsilon} \rightarrow \chi_\Omega$ strongly in $L^2(\Omega)$.

Let us consider the following sequence of regularized OCPs associated with domains Ω_ε

$$\left\{ \left\langle \inf_{(u,v,y) \in \Xi_\varepsilon} I_\varepsilon(u, v, y) \right\rangle, \quad \varepsilon \rightarrow 0 \right\}, \quad (13)$$

where

$$I_\varepsilon(u, v, y) := \|y - y_d\|_{H_0^1(\Omega_\varepsilon; \Gamma_D)}^2 + \|u\|_{L^2(\Gamma_N)}^2 + \frac{1}{\varepsilon^\alpha} \|v\|_{H^{-\frac{1}{2}}(\Gamma_\varepsilon)}^2, \quad (14)$$

$$\Xi_\varepsilon = \left\{ (u, v, y) \left| \begin{array}{l} -\operatorname{div}(\nabla y + A\nabla y) = f \quad \text{in } \Omega_\varepsilon, \\ y = 0 \text{ on } \Gamma_D, \quad \partial y / \partial \nu_A = u \text{ on } \Gamma_N, \\ \partial y / \partial \nu_A = v \text{ on } \Gamma_\varepsilon, \\ u \in L^2(\Gamma_N), \quad v \in H^{-\frac{1}{2}}(\Gamma_\varepsilon), \quad y \in H_0^1(\Omega_\varepsilon; \Gamma_D). \end{array} \right. \right\} \quad (15)$$

Here, $y_d \in H_0^1(\Omega, \Gamma_D)$ and $f \in L^2(\Omega)$ are given functions, ν is the outward normal unit vector at Γ_N and Γ_ε to Ω_ε , $v \in H^{-\frac{1}{2}}(\Gamma_\varepsilon)$ is considered as a fictitious control, and α is a positive number such that

$$\varepsilon^{-\alpha} \mathcal{H}^{N-1}(\Gamma_\varepsilon) \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

Theorem

For every $\varepsilon > 0$ there exists a unique minimizer $(u_\varepsilon^0, v_\varepsilon^0, y_\varepsilon^0) \in \Xi_\varepsilon$ to the problem $\langle \inf_{(u,v,y) \in \Xi_\varepsilon} I_\varepsilon(u, v, y) \rangle$.

In order to study the asymptotic behavior of the sequences of admissible solutions in the scale of variable spaces, we adopt the following concept.

Definition

We say that a sequence $\{(u_\varepsilon, v_\varepsilon, y_\varepsilon) \in \Xi_\varepsilon\}_{\varepsilon > 0}$ weakly converges to $(u, y) \in L^2(\Gamma_N) \times H_0^1(\Omega; \Gamma_D)$ in the scale of spaces

$$\left\{ L^2(\Gamma_N) \times H^{-\frac{1}{2}}(\Gamma_\varepsilon) \times H_0^1(\Omega_\varepsilon; \Gamma_D) \right\}_{\varepsilon > 0}, \text{ if}$$

$$u_\varepsilon \rightharpoonup u \text{ in } L^2(\Gamma_N), \quad y_\varepsilon \rightharpoonup y \text{ in } H_0^1(\Omega_\varepsilon; \Gamma_D),$$

$$\text{and } \sup_{\varepsilon > 0} \frac{1}{\mathcal{H}^{N-1}(\Gamma_\varepsilon)} \|v_\varepsilon\|_{H^{-\frac{1}{2}}(\Gamma_\varepsilon)}^2 < +\infty.$$

Main Results

Theorem

Let $A \in L^2(\Omega; \mathbb{S}^N)$ be a funnel-type stream matrix such that

the equality $[y, y] = 0$ does not hold in D .

Let $\{\Omega_\varepsilon\}_{\varepsilon>0}$ be a sequence of perforated subdomains of Ω associated with matrix A . Then problem $\langle \inf_{(u,y) \in \Xi} I(u, y) \rangle$, where $y_d \in H_0^1(\Omega, \Gamma_D)$ and $f \in L^2(\Omega)$ are given functions, is a variational limit of sequence (13)–(15) as the parameter ε tends to zero.

Main Results

Theorem

Let $A \in L^2(\Omega; \mathbb{S}^N)$ be a funnel-type stream matrix such that

the equality $[y, y] = 0$ does not hold in D .

Let $y_d \in H_0^1(\Omega, \Gamma_D)$ and $f \in L^2(\Omega)$ be given functions. Let $\{(u_\varepsilon^0, y_\varepsilon^0) \in \Xi_\varepsilon\}_{\varepsilon > 0}$ be a sequence of optimal solutions to regularized problems (13)–(15). Then a unique optimal solution to OCP (9)–(12) is attainable in the following sense

$$u_\varepsilon^0 \rightharpoonup u^0 \text{ in } L^2(\Gamma_N), \quad y_\varepsilon^0 \rightharpoonup y^0 \text{ in } H_0^1(\Omega_\varepsilon; \Gamma_D),$$

$$\inf_{(u, y) \in \Xi} l(u, y) = l(u^0, y^0) = \lim_{\varepsilon \rightarrow 0} l_\varepsilon(u_\varepsilon^0, v_\varepsilon^0, y_\varepsilon^0).$$

Thank you for your unlimited patience

HAVE A NICE DAY

