

Two applications of functional data

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Outline

- 1 Improving predictions of stellar parameters
- 2 Causality with functional data
- 3 Bibliography

Outline

1 Improving predictions of stellar parameters

2 Causality with functional data

3 Bibliography

- This first part of the talk is already published.
- This is a joint work with Robbiano, S. and Curé, M. [4].

Problem

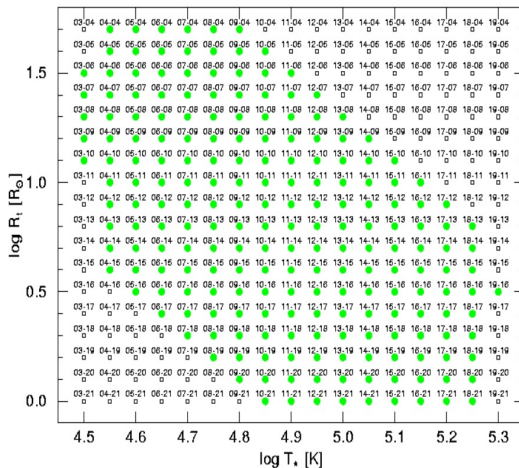
(Astrophysicist) Goal : determine the temperature (T) and the radius of a star (R)

Popular method

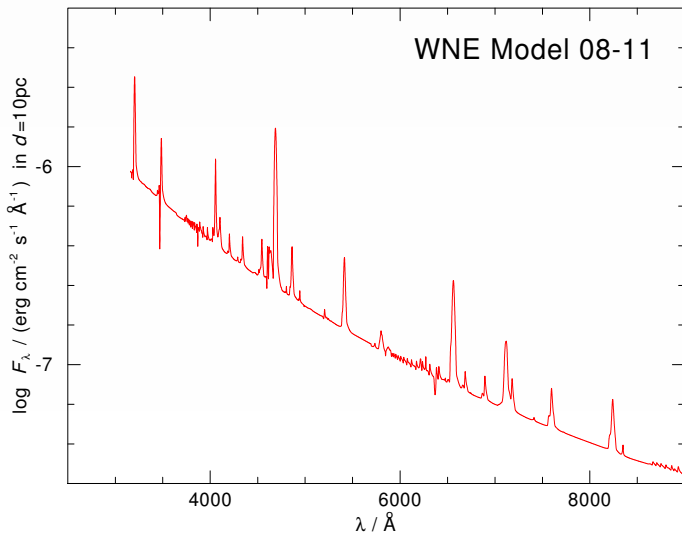
- Create a physic model depending of T and R to build spectrum
- Generate a grid of simulated spectrum
- Compute the closest spectrum of the grid to the real data
- Say that they have the same T and R

Grid

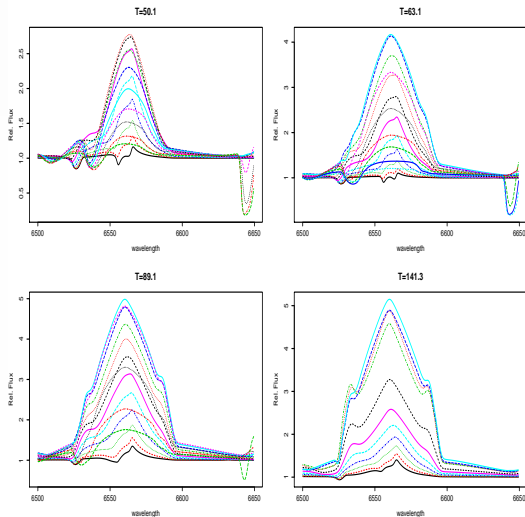
WNE grid: • = existing models

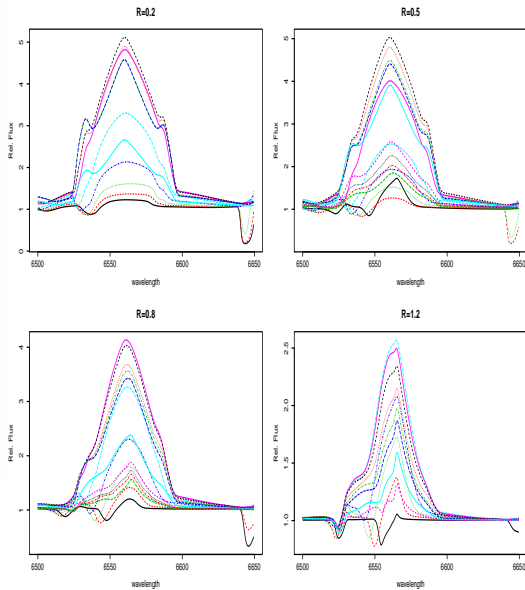


Example



Data





Functional Model

Functional linear model

$$Y = \alpha_1 + \langle \beta, X \rangle + \varepsilon \quad (1.1)$$

Approximation of X

$$X(t) = \sum_{k=1}^p x_k \rho_k(t) + r_p,$$

where $x_k = \int_K X(t) \rho_k(t) dt$ and r_p is an error.

Approximation of β

$$\beta(t) = \sum_{k=1}^p b_k \rho_k(t) + r b_p$$

Functional Model multi-lines

$$\begin{cases} Y_i^{(1)} = \alpha_1 + \sum_{j=1}^M \langle \beta_{1,j}, X_{i,j} \rangle + \varepsilon_i \\ Y_i^{(2)} = \alpha_2 + \sum_{j=1}^M \langle \beta_{2,j}, X_{i,j} \rangle + \varepsilon'_i \end{cases} \quad (1.3)$$

$$X_{i,j} = \sum_{k=1}^p x_{ijk} \rho_k^j + r_{ijp},$$

where $x_{ijk} = \int_K X_{i,j}(t) \rho_k^j(t) dt$ and r_{ijp} is an error. We decompose the parameters $\beta_{1,j}$ and $\beta_{2,j}$ in the same basis with the same notation. Then, we have

$$\begin{cases} Y_i^{(1)} = \alpha_1 + \sum_{j=1}^M \sum_{k=1}^p \beta_{1,jk} x_{ijk} + \epsilon_i \\ Y_i^{(2)} = \alpha_2 + \sum_{j=1}^M \sum_{k=1}^p \beta_{2,jk} x_{ijk} + \epsilon'_i. \end{cases} \quad (1.4)$$

If we note \mathbf{X}_j the matrix $(x_{ijk})_{i=1\dots n, k=1, \dots, p}$ we have

$$\begin{cases} \mathbf{Y}^{(1)} = \alpha_1 + \sum_{j=1}^M \mathbf{X}_j \beta_{1,j} + \epsilon_i \\ \mathbf{Y}^{(2)} = \alpha_2 + \sum_{j=1}^M \mathbf{X}_j \beta_{2,j} + \epsilon'_i. \end{cases} \quad (1.5)$$

Prediction Methods

- Problem : Ordinary least squares estimator is very unstable
- Robust linear regression
- Ridge regression

Others models

- Nonparametrics methods namely Ferraty et Vieu [1]
- Lasso
- Elastic net

Evaluation of the prediction

$$\begin{cases} \widehat{Y^{(1)}} = \hat{\alpha}_1 + \sum_{j=1}^M \langle \hat{\beta}_{1,j}, x_j \rangle \\ \widehat{Y^{(2)}} = \hat{\alpha}_2 + \sum_{j=1}^M \langle \hat{\beta}_{2,j}, x_j \rangle \end{cases}$$

$$RMSE(\beta_l) = \sqrt{\frac{1}{n} \sum_{i=1}^n |Y_i^{(l)} - \hat{Y}_i^{(l)}|^2}.$$

$$\Gamma ME(\beta) = \sqrt{\frac{1}{n} \sum_{i=1}^n (Y_i - \hat{Y}_i, Y_i - \hat{Y}_i)_{\Gamma}}.$$

Prediction procedure

- We split the database in 5 parts of equal size.
- We use 3 parts (the learning set) to compute the parameter β_1^p and β_2^p for several parameter p (in practice we choose $p = 1 + 4k$ for $k = 1, \dots, 10$).
- We choose the parameter p that minimize the mean Γ error on the validation.
- We evaluate the prediction accuracy of our method on the last part of the data set (testing set).

- 1 (Input.) A training dataset $\mathcal{D} = (\mathbf{X}, \mathbf{Y})$ of size n , \mathcal{A} a prediction algorithm, X_f an observation.
- 2 (Estimation) Compute $\hat{\mathbf{Y}} = \mathbf{X}\hat{\beta}$ using \mathcal{D} and \mathcal{A} . Set $\hat{r} = (\hat{r}_1, \dots, \hat{r}_n) = \mathbf{Y} - \hat{\mathbf{Y}}$ the residues.
- 3 (Iterations.) For $t = 1, \dots, T$,
 - 1 (Sample.) Draw with replacement from \hat{r} a sample $r^* = (r_1^*, \dots, r_n^*)$ and r_f^* . Create $\mathcal{D}^* = (\mathbf{X}, \mathbf{Y}^*)$ where $\mathbf{Y}^* = \mathbf{X}\hat{\beta} + r^*$
 - 2 (Learning.) Use \mathcal{A} and \mathcal{D}^* to compute $\hat{\beta}^*$. Keep $B_t^* = X_f\hat{\beta} - X_f\hat{\beta}^* + r_f^*$.
- 4 (Output) A prediction interval $\tilde{I} = [X_f\hat{\beta} + q^*; X_f\hat{\beta} + Q^*]$ where q^* (resp. Q^*) is the empirical quantile at level $\alpha/2$ (resp. $1 - \alpha/2$) of $B^* = (B_1^*, \dots, B_T^*)$.

Results

Table: Comparison of methods with Fourier decomposition : prediction.

		LM		Robust LM		Ridge	
	Astro	Brut	Norm	Brut	Norm	Brut	Norm
$\gamma^{(1)}$	0.171	0.088	0.068	0.062	0.060	0.080	0.066
$\gamma^{(2)}$	0.143	0.089	0.071	0.060	0.066	0.075	0.081
$ _{\Gamma}$	0.437	0.280	0.211	0.189	0.189	0.231	0.233
Nbase	—	7	5	7	7	7	7

Results

Table: Comparison of methods with spline decomposition : prediction.

		LM		Robust LM		Ridge	
	Astro	Brut	Norm	Brut	Norm	Brut	Norm
$\gamma^{(1)}$	0.171	0.119	0.116	0.116	0.120	0.079	0.060
$\gamma^{(2)}$	0.143	0.102	0.102	0.096	0.112	0.075	0.067
$ _r$	0.437	0.322	0.315	0.302	0.317	0.235	0.200
Nbase	—	5	5	5	5	21	13

Table: Comparison of methods with Fourier decomposition : coverage probabilities at 95 % .

	Astro	LM		Robust LM		Ridge	
		Brut	Norm	Brut	Norm	Brut	Norm
Coverage $Y^{(1)}$	0.871	0.918	0.896	0.908	0.919	0.944	0.957
Coverage $Y^{(2)}$	0.910	0.941	0.966	0.915	0.916	0.951	0.970

Table: Comparison of methods with spline decomposition : coverage probabilities at 95 % .

		LM			Robust LM		Ridge	
		Astro	Brut	Norm	Brut	Norm	Brut	Norm
Coverage	$Y^{(1)}$	0.871	0.923	0.919	0.928	0.909	0.986	0.980
Coverage	$Y^{(2)}$	0.910	0.949	0.946	0.919	0.885	0.986	0.986

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1 Improving predictions of stellar parameters

2 Causality with functional data

3 Bibliography

- This second part is a joint work with Raissi, H.

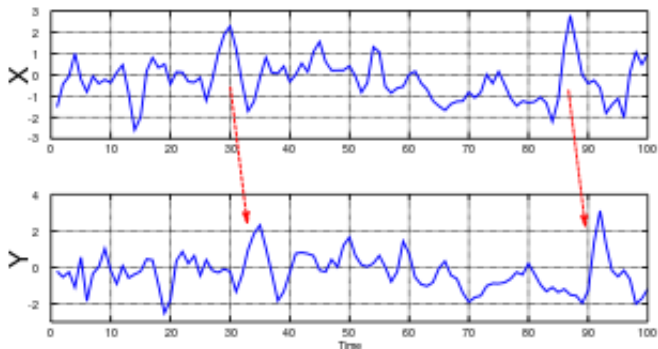


Figure: An example of causality with two time series. Ref : Wikipedia

Two principles

Granger [2] in 1969 propose the following definition for causality of two time series based on two principles :

- 1 The cause happens prior to its effect.
- 2 The cause has unique information about the future values of its effect.

As a consequence, the consideration of the cause allows to improve the prediction of the effect.

Mathematical definition

- Let $\{X_t, t \in \mathbb{Z}\}$ and $\{Y_t, t \in \mathbb{Z}\}$ be two time series.
- Let $A_t = \{Z_{k,t}, k \in I\}$, $I \subset \mathbb{Z}$, $\{X_t, Y_t\} \subseteq A_t$.
- Definitions : $\bar{X}_t = \{X_s, s \leq t\}$, $\bar{Y}_t = \{Y_s, s \leq t\}$,
 $\bar{A}_t = \bigcup_{s \leq t} A_s$.

Let B an information set and $\mathbb{P}(Y_t|B)$ the best linear predictor,

$$\varepsilon(Y_t|B) = Y_t - \mathbb{P}(Y_t|B), \quad (2.6)$$

$$\sigma^2(Y_t|B) = \mathbb{E} [\varepsilon(Y_t|B)^2]. \quad (2.7)$$

Mathematical definition

Definition (Granger, 1969)

The variable X causes the variable Y iff for at least one value of t :

$$\sigma^2(Y_{t+1}|\bar{A}_t) < \sigma^2(Y_{t+1}|\bar{A}_t \setminus \{\bar{X}_t\}). \quad (2.8)$$

One Example

With an autoregressive model, we have that :

$$Y_t = \alpha + \sum_{k=1}^K \gamma_k Y_{t-k} + \sum_{k=1}^L \beta_k X_{t-k} + \epsilon_t$$

the variable X does not cause the variable Y iff

$$\beta_k = 0, \quad \forall k = 1, \dots, L.$$

Operator of covariance

$$\forall u \in L^2([0, 1]), \Gamma u = \mathbb{E} (\langle X_i - \mathbb{E}(X_i), u \rangle (X_i - \mathbb{E}(X_i))) . \quad (2.9)$$

Definition (Causality)

We say that Y is causing X if $\Gamma_{\varepsilon(X|\overline{U-Y})} - \Gamma_{\varepsilon(X|U)}$ is a positive definite operator.

The model

$$\begin{cases} X_t = \rho_{11}(X_{t-1}) + \rho_{12}(Y_{t-1}) + \varepsilon_{1t}, \\ Y_t = \rho_{21}(X_{t-1}) + \rho_{22}(Y_{t-1}) + \varepsilon_{2t}, \end{cases}$$

where $\varepsilon_1, \varepsilon_2$ are errors and the $\rho_{..}$ are operators.

The null hypothesis

The test we want to perform is then

$$H_0 : \rho_{12} = 0, \quad (2.10)$$

against the alternative

$$H_1 : \rho_{12} \neq 0.$$

- 1 Data X and Y
- 2 Estimation of the parameters ρ
- 3 Estimation of the errors ε
- 4 Test the equality of operators based on the errors

Zhang and Shao (2015) [5] recently have proposed :

- a test procedure to compare the covariance operators of two mean zero stationary functional time series.

The null hypothesis is

$$H_0 : \Gamma_X = \Gamma_Y, \quad (2.11)$$

against the alternative

$$H_1 : \Gamma_X \neq \Gamma_Y,$$

Define $\{\hat{\lambda}_{XY}^j\}$ and $\{\hat{\phi}_{XY}^j\}$ the eigenvalues and eigenfunctions of

$$\hat{\Gamma}_{XY} = \frac{1}{2N} \left(\sum_{i=1}^N X_i \otimes X_i + Y_i \otimes Y_i \right).$$

Let $\hat{\Gamma}_{X,m} = 1/m \sum_{i=1}^m X_i \otimes X_i$. Let $\{\hat{\lambda}_{X,m}^j\}$ and $\{\hat{\phi}_{X,m}^j\}$ be the eigenvalues and eigenfunctions of $\hat{\Gamma}_{X,m}$. Similar quantities are defined for the second sample.

Let K be a fixed user-chosen number and

$$c_k^{i,j} = \langle (\hat{\Gamma}_{X,[k/2]} - \hat{\Gamma}_{Y,[k/2]})(\hat{\phi}_{XY}^i), \hat{\phi}_{XY}^j \rangle, \quad 2 \leq k \leq 2N, \quad 1 \leq i, j \leq K.$$

Denote by $\hat{\alpha}_k = \text{vech}(C_k)$, with $C_k = (c_k^{i,j})_{i,j=1}^K$. To take the dependence into account, they introduce a self-normalized matrix :

$$V = \frac{1}{4N^2} \sum_{k=1}^{2N} k^2 (\hat{\alpha}_k - \hat{\alpha}_{2N})(\hat{\alpha}_k - \hat{\alpha}_{2N})'.$$

The test statistic is then

$$G = 2N \hat{\alpha}_{2N}' V^{-1} \hat{\alpha}_{2N}.$$

Define :

- $B_q(r)$ as a q -dimensional vector of independent Brownian motion
- $W_q = B_q'(1)J_q^{-1}B_q(1)$, where

$$J_q = \int_0^1 (B_q(r) - rB_q(1))(B_q(r) - rB_q(1))' dr.$$

- The critical values of W_q have been tabulated by Lobato (2001) [3].

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